

SHENGJIE XU

sxu88@ucsc.edu | shengjie-xu.com

EDUCATION

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- University of California, Santa Cruz** | *MS in Electrical & Computer Engineering* Sept. 2021 - 2023 (expected)
Santa Cruz, CA
Advisor: Leilani H. Gilpin.
• cumulative GPA: 3.84
- Hebei University of Technology** | *BSc in Mechanical Engineering, Vehicle Engineering minor* Sept. 2007 – June 2011
Tianjin, China
Advisor: Zhanqun Shi.

RESEARCH INTERESTS

Trustworthy/Explainable AI, Physical Scene Understanding, 3D Vision, Robotics and Self-driving Cars

PROFESSIONAL EXPERIENCE

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- University of California, Santa Cruz** | *Graduate Student Researcher* Dec. 2021 – present
Santa Cruz, CA
An Explainable Artificial Intelligence Framework for Neural Networks Training
• An explainability analysis of LiDAR inference model by using SHAP (Co-advised by James Davis).
• Generate Danger-KITTI corner cases by manipulating car's pose, color, and shape ([GitHub](#)).
• A proposal of developing explainable AI feedback with GAN/adversarial generated datasets.
- China Automotive Technology and Research Center** | *Sr. Researcher* Jan. 2017 – Sept. 2021
Tianjin, China
Led an R&D team of computer vision in automotive applications.
• Developed an autonomous driving test platform based on a virtual Thunderhill track using OpenStreetMap, Unreal Engine, and CARLA by importing optimized waypoints and autonomously drove the vehicle model on the path at a maximum speed of 150kph.
• Developed a disparity estimation algorithm for reconstructing the 3D model of a road surface to estimate real-time wheel force. Programmed a real-time convolution pipeline to visualize the predicted wheel force via PyQtGraph.
• Implemented YOLO-v3 for real-time road type detection and classification.
• Created a data analysis system to investigate the black-box modeling properties of the wheel force by Multi-Layer Perceptron and LSTM.
• Founded an internal learning group dedicated to bringing self-driving machine learning knowledge to help staff across the company on the topics of CNN, Computer Vision, linear SVM, UKF/EKF, Particle Filter, A* planning.
- China Automotive Technology and Research Center** | *Sr. Engineering Manager* Sept. 2011 – June 2019
Tianjin, China
Led vehicle testing team in CATARC.
• Founded a Road Simulation team to serve Road Load Data Acquisition and system-identification-based dynamical road simulation.

PUBLICATIONS

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- A Framework for Generating Dangerous Scenes for Testing Robustness* NeurIPS Workshop on TEA 2022
Shengjie Xu, Lan Mi, Leilani H. Gilpin
- DANGER: A Framework of Danger-Aware Novel Dataset Generator Extension for Robustness Test of Machine Learning* BayLearn 2022
Shengjie Xu, Leilani H. Gilpin
- Integrated Model Predictive Control and Adaptive Unscented Kalman Filter for Semi-active Suspension System Based on Road Classification* SAE Technical Paper 2020
Zhenfeng Wang, Shengjie Xu, Fei Li, Xinyu Wang, Jiansen Yang, Jing Miao
- Modified Quasi-Newton Optimization Algorithm Based Iterative Learning Control for Multi-axial Road Durability Test Rig* IEEE Access 2019
Xiao Wang, Dacheng Cong, Zhidong Yang, Shengjie Xu, Junwei Han
- The Synthetic 3DOF Wheel Force for Passenger Vehicle Based on Predicted Frequency Response Function Model* SAE Technical Paper 2018
Shengjie Xu

COURSES

CSE 201 Analysis of Algorithms <i>Instructor: Seshadhri Comandur</i>	Winter 2022
CSE 160 Introduction to Computer Graphics <i>Instructor: James E. Davis</i>	Fall 2021
<ul style="list-style-type: none">• Johnny 5. A WebGL-based blocky 3D animal won 2nd Overall Best prize in the Hall of Fame of CSE 160.• Escape from Wolfenstein. A WebGL-based first-person shooter game won Best Story/Game prize in the Hall of Fame of CSE 160.	
ECE 240 Introduction to Linear Dynamical Systems <i>Instructor: Gabriel Hugh Elkaim</i>	Fall 2021
AM 214 Applied Dynamical Systems <i>Instructor: Daniele Venturi</i>	Fall 2021

HONORS/AWARDS & CERTIFICATES

Stanford Certificate of Completion on <i>ICME Summer Workshops 2022 — Fundamentals of Data Science</i>	Aug. 2022
San Diego Supercomputer Center Training Certificate on <i>High Performance Computing (HPC)/ Cyber-infrastructure (CI) Training Series</i>	Jan. 2022 – May. 2022
Coursera Course Certificates on <i>Visual Perception for Self-Driving Cars, Introduction to Self-Driving Cars</i>	Feb. 2020 – Mar. 2020
Udacity Course Certificates on <i>Computer Vision and Deep Learning, Sensor Fusion, Localization, and Control</i>	Mar. 2018 – Aug. 2018
Automotive Engineering Research Institute <i>Excellent Core Researcher</i>	2015
Automotive Engineering Research Institute <i>Excellent Core Researcher</i>	2013
Distinguished Undergraduate Thesis Award	2011

INVITED TALKS

International Forum on Reliability Session of SAE China	Sept. 2019
<i>"The Application of Hybrid Simulation Road Simulation in Automotive Durability Development"</i>	Shanghai, China
SAE World Congress Experience	Apr. 2018
<i>"The Synthetic 3DOF Wheel Force for Passenger Vehicle Based on Predicted Frequency Response Function Model"</i>	Detroit, MI

PROFESSIONAL SERVICE

- Paper Reviewer**
- Conference on Neural Information Processing Systems (**NeurIPS 2022**)
 - SAE International World Congress Experience (**SAE WCX 2018**)

TEACHING EXPERIENCE

CSE30: Programming Abstractions: Python <i>Teaching Assistance, UC Santa Cruz</i>	Spring 2022, Fall 2021
ECE121: Microcontroller System Design <i>Teaching Assistance, UC Santa Cruz</i>	Winter 2022

RESEARCH MENTORING

Wangyuan Xing <i>Undergraduate student at Hebei University of Technology</i>	Jan. 2021 – June 2021
<ul style="list-style-type: none">• <i>Trajectory Optimization and Control Simulation for Driverless Racecar Based on CARLA. Best Paper</i>	
Pengchao Wang <i>Undergraduate student at Hebei University of Technology</i>	Jan. 2021 – June 2021
<ul style="list-style-type: none">• <i>Unreal Engine based Autonomous Vehicle Traffic Scene Construction and Pedestrian Detection</i>	
Zhaoran Wang <i>Undergraduate student at Hebei University of Technology</i>	Jan. 2021 – June 2021
<ul style="list-style-type: none">• <i>Research and Application of Pavement Information Reconstruction Based on Stereo Vision. Best Paper</i>	

SKILLS

Programming Languages: Python, HTML, JavaScript, MATLAB, C++, Java, L^AT_EX, Julia
Tools: OpenCV, PyTorch, Tensorflow, Haiku/JAX, OpenGL/WebGL, Scikit-learn, CARLA, Unreal Engine, PyBullet, AWS EC2, Linux (Ubuntu), Git, Docker

SPECIALTY

Fine Arts: My Renaissance-style practicing drawings are available at [here](#).
Liberal Arts: Reading books about economic liberalism, history, democracy, constitutionalism, and entrepreneurship.