

# SHENGJIE XU

CATARC AERI Advanced Technology Department  
68 Xianfeng East Road,  
Dongli District, Tianjin, 300070

<https://www.linkedin.com/in/shengjiexu/>  
[jayhsu0627@gmail.com](mailto:jayhsu0627@gmail.com)  
+86-1761-221-8861

## RESEARCH PROJECTS

### Real-Time Object Detector and 3D Reconstruction of Road, Researcher

A project to investigate how computer vision could link the 2D dimension and physical force domain. The idea was innovated by the time-consuming customer correlation project in traditional vehicle development, I use this insight to develop a method and tool for object detection and force prediction. Implemented an object detection algorithm from YOLO-v3 for real-time road type identification. I built a disparity estimation algorithm for reconstructing the 3D model of a road surface to estimate real-time wheel force.

### Autonomous BLUE project, Co-leader and Researcher

Co-founded an advanced technology department to shift AERI's research interests on electrified vehicle and autonomous driving technology. Lead and build an electrified BLUE steer-by-wire prototype vehicle. The planned steer-by-wire system consists of three redundant Audeesse controllers, a steering column clutch, one Field Oriented Control (FOC) BLDC motor as steering column input, two steering rack DC motors with redundancy consideration. Integrate road 3D reconstruction CV algorithms with Audeesse controllers for path planning and control.

## EDUCATION

2008-2011 **Hebei University of Technology**, Tianjin, PRC  
BSc In Vehicle Engineering  
GPA: 2.9/4.0, Top 22%  
Advisor: Zhanqun Shi

2007-2008 **Hebei University of Technology**, Tianjin, PRC  
Major In Economics  
GPA: 2.85/4.0

## AWARDS & CERTIFICATES

Coursera Course Certificate on *Visual Perception for Self-Driving Cars*, 2020  
Coursera Course Certificate on *Introduction to Self-Driving Cars*, 2020  
Udacity Course Certificate on *Sensor Fusion, Localization, and Control*, 2018  
Udacity Course Certificate on *Computer Vision and Deep Learning*, 2018  
Automotive Engineering Research Institute Excellent Core Researcher, 2015  
Automotive Engineering Research Institute Excellent Core Researcher, 2013  
Distinguished Undergraduate Thesis Award, 2011  
National Computer Rank Examination Certificate C++, 2008

## EMPLOYMENT & PROJECTS

2011-PRESENT **China Automotive Technology and Research Center**, Automotive Engineering Research Institute. Several projects:

2019 *Air Spring Controller*. Researcher  
Employed the Siemens S7-200 PLC, compressed air pump, and proportional air valve to construct an air suspension ride height-adjusting system for Daimler AG's prototype vehicle. Enabled the system to adjust the vehicle's ride height to a designated value only within 5 seconds.

2017-2018 *Wheel Force Prediction Algorithm*. Researcher  
Discovered the strong coherence between wheel hub acceleration and wheel force by frequency response function. Programmed a real-time convolution pipeline to predict wheel force via Python. Investigated in black-box modelling by multilayer perceptron and Long short-term memory.

2012-2019 *Road Simulation*. Team Leader  
*HSRC Technology*. Developed iterative technology grounded on virtual Road Load Data Acquisition and Hybrid Simulation Response Convergence (HSRC) with adopting the self-developed strain gauge three-component load cell as the feedback signal of suspension in iteration, and capitalizing on HSRC to integrate real physical models, virtual FTire model, with the digital road to calculate drive file.  
*Global Outreach*. Visited the Chrysler Technical Center in Fiat Chrysler Automobiles, Aurben Hill, MI, and the Test Center in the headquarter of Daimler AG in Sindelfingen, Germany as technical partner upon invitation.  
*Road Simulation Team*. I founded two Road Simulation Team while building the standardized iterative operation workflows. I turned the testing team over to my teammate in 2019. These two business units consistently contributing revenue of twenty million RMB annually.

2012-2014 *Road Load Data Acquisition (RLDA) and Data Analysis*. Team Leader  
I founded an RLDA team to cultivate our technical expertise in instrumentation, polarity check, strain gauge application, calibration, and on-the-site troubleshooting. I handed the testing team over to my teammate in 2014, this unit has been consistently contributing revenue of six million RMB each year.  
Expertise in up to 200 channels simultaneously data collection against the MIL-STD working condition and ensured data quality.  
We developed a serial of three-component load cells based on strain gauge with the crosstalk coupling between channels being less than 3%. The finished product reaching 10 kN and 70 kN of capacity can be equipped in various parts on a vehicle, including chassis sub-frame and engine mounting.

2011-2012 *Vehicle Dynamics Testing*. Test Development Engineer  
Configured various instruments and sensors and established standard testing procedures under the ISO/SAE/GB/OEM to fulfill clients' demands.  
Executed data processing and programmed efficient pipeline by nCode, FlexPro, and VBA to meet the signal processing requirements. Contributed to the road testing capability based on vehicle dynamics, set up a corresponding team, handed the instruments and knowledge to colleague in 2012.

2018-PRESENT **XERUS Engineering Technology**, Founder  
2020 *Side Impact Test Rig*. We cooperated with Mechatronic Vehicle Systems Lab at the University of Waterloo to propose a PLC-driven test rig that could introduce predefined energy into the wheel-suspension assembly for the Daimler Greater China Ltd RD Tech Center China. The proposed system was composed of a pendulum, an adjustable pendulum head, and a Beckhoff PLC system control impact energy by changing impact weight, releasing height, and triggering impact force measurement in one second. The up-to-one-ton moving pendulum triggered a high-speed light curtain, and the 30 channels of acceleration and force between the pendulum system and the specimen could be simultaneously collected--the complete process is less than one second. The compiled proposal was highly recognized by the technical manager of Daimler AG China.

## PERSONAL PROJECTS

2020 **Self-Driving Cars**, Coursera  
*Vehicle Dynamic Modelling with Python*. Constructed longitudinal and lateral dynamic models for a vehicle and created controllers that regulated the speed and path tracking performance with Python.

*Vehicle Controller in Python*. Developed the control code to navigate a self-driving car around a racetrack in the CARLA simulation environment.  
*Localization*. Implemented the Error-State Extended Kalman Filter to localize a vehicle using data from the CARLA simulator.  
*Visual Perception and Segmentation*. Developed algorithms that identified bounding boxes for objects in the scene and defined the boundaries of the drivable surface

2017-2018

**Self-Driving Car Nano Degree**, Udacity

*Computer Vision for Lane Detection*, Developed an lane detection algorithm with Camera Calibration, Sobel Threshold, Canny edge detection, and Hough transform packages of OpenCV in Python.

*Traffic Signs Detection by CNN*, Trained a LeNet-5 to detect German traffic signs with a validation accuracy higher than 98%.

*CNN based Steering*, Built a CNN in Keras on Amazon AWS cloud that predicted steering angles from images collected from a simulator, and then validated the model by driving a car in a racetrack of simulator without leaving the road.

*SVM based Vehicle Detection*, Performed a Histogram of Oriented Gradients (HOG) feature extraction on a labeled training set of images and trained a classifier Linear SVM classifier to detect vehicle appeared in each frame.

*State Estimation and Localization*, Utilized Unscented Kalman Filter and Extended-Kalman-Filter in C++ to estimate the state of a moving object of interest with noisy Lidar and radar measurements, and built PID and MPC controller for vehicle trajectory control.

*Particle Filter Based Localization*, Implemented a 2-dimensional particle filter in C++ with given a map and initial GPS localization information to localize the vehicle position from observation and control data.

2017

**Artificial Intelligence for Robotics**, Udacity

Developed several Python scripts to master the knowledge in localization, A\* planning, Kalman filters, particle filters, PID control, and SLAM

## CO-OP PROJECTS

2011

**Hebei University of Technology**.

*Real-time down-force measurement system for Formula Student China 2011*. Obtained the eligibility of participating in FSC for HEBUT for the first time with Prof. Zhanqun Shi. Guided our team to design and manufacture the chassis, drive system, and aerodynamics modules. Led members to develop measurement system based on strain gauge and data logger.

2010

**China Automotive Technology and Research Center**.

*Wheel Encoder Measurement*, Led a team to improve the measurement quality for ABS test: designed a universal encoder fixture by AutoCAD to fit different PCD of wheels; established a VBA data processing script to enhance efficiency.

## CORE SKILLS

**Languages & Tools:** C++, Python, MATLAB, OpenCV, Linux, ROS, Docker, Git, Tensorflow, Keras, Scikit-learn, Arduino, VBA, Solidworks, MSC.Adams, Amazon AWS EC2, putty, CARLA

**Data Acquisition & Analysis:** nCode, DEWESoft, HBM eDAQ, Mars Labs Titan, MTS 793/RPC Pro, IST RS Console/TWR

**Instruments:** Accelerometer, Strain Gage Load Cell, Steering Wheel Sensor, Kistler/MS/MTS/ Wheel Force Transducer, Telemetry, Slip Ring

**Knowledge:** Kalman filter, Particle Filter, Computer Vision, Planning and Control, Deep Learning, Embedded Systems, Sensors: IMU, camera, GPS, Fatigue Analysis, Public Road and Proving Ground Correlation, Vehicle Development

## PEER-REVIEWED PUBLICATIONS

### JOURNALS

Zhenfeng Wang, Jiansen Yang, Zhongliang Han, **Shengjie Xu**. A Study on Vehicle Transient Roll Control Based on Fuzzy Observer [J] on *Journal of Northeastern University (Natural Science)*, Manuscript Accepted

Zhenfeng Wang, Shengjie Xu, Fei Li, Xinyu Wang, Jiansen Yang, Jing Miao. [Integrated Model Predictive Control and Adaptive Unscented Kalman Filter for Semi-active Suspension System Based on Road Classification](#) on *SAE Technical Paper*, 2020

Xiao Wang, Dacheng Cong, Zhidong Yang, **Shengjie Xu**, Junwei Han. [Modified Quasi-Newton Optimization Algorithm Based Iterative Learning Control for Multi-axial Road Durability Test Rig](#) on *IEEE Access*, 2019

Wang, Xiao, Dacheng Cong, Zhidong Yang, **Shengjie Xu**, and Junwei Han. [Iterative Learning Control with Complex Conjugate Gradient Optimization Algorithm for Multiaxial Road Durability Test Rig](#) on *Proceedings of the Institution of Mechanical Engineers, Part C: Journal of Mechanical Engineering Science*, 2018

Wei Li, Guang Yang, **Shengjie Xu**. A Study of the Effect of the Control Strategy of a Six-degree-of-freedom Road Simulation Test Stand on Iterative Results on *Passenger Car Technology and Research*, 2018

Baoming Chai, Decheng Jin, Wei Li, **Shengjie Xu**, Shao Zhang. Determination of Automotive Customer Correlation Generated Target Load Profiles [J] on *Technology Innovation and Application*, 2015

Dongming Xie, Bin Qiu, **Shengjie Xu**, Jianjun Liu. Overview of Objective Evaluation Indicators and Methods for Road Testing of Passenger Car Tires on *Automotive Engineering*, 2014

Peng Ji, Jiankun Sun, Muqiong Duan, Jiansen Yang, **Shengjie Xu**. A Study on the Impact of Proving Ground Correlation on Automotive Reliability Test [J] on *The Hebei University of Technology Journal (Natural Science Edition)*, 2013

Chao Lin, Baoming Chai, **Shengjie Xu**. The Lightweight Design of Body in White Based on the Sensitivity Analysis on *The Hebei University of Technology Journal (Natural Science Edition)*, 2013

### CONFERENCE PAPERS

**Shengjie Xu**. [The Synthetic 3DOF Wheel Force for Passenger Vehicle Based on Predicted Frequency Response Function Model](#), *SAE Technical Paper*, 2018-01-0123, 2018

**Shengjie Xu**, Bo Feng, Zhiqiang Zhao. The Reasons of Ripple Interference of Wheel Force Transducer and Data Correction Method on *The International Conference of NVH Technology*, 2016

### PATENTS & DESIGN PATENTS

Daming Jiang, Xinyu Wang, Wei Li, Guang Yang, **Shengjie Xu**, Huaiyu Ye, Xuepeng Cui, Jinming Wu, Wenjie Yin. [A Vehicle Hoisting Device for Full Vehicle Road Simulation Testing Rig](#) [P], CN211366674U, 2020

Mingyue Zhou, Liang Kou, Xinyu Wang, Tianji Feng, Yichao Li, Weili, **Shengjie Xu**. [General Type Braking Bench Test Clamping Device](#) [P], CN210375716U, 2020

**Shengjie Xu**, Guang Yang, Zhiqiang Zhao, Wei Li. [A Hexagon Outer Part Fixture for Wheel Force Transducer](#) [P], CN209131877U, 2018

**Shengjie Xu**, Xinyu Wang, Wei Li, Zhiqiang Zhao, Guang Yang, Bo Feng, Wang Zhang, Mingyue Zhou. [A Fix-Reaction Fixture of Suspension Fatigue Test for Road Simulation Test](#) [P], CN207689147U, 2018

### INVITED TALKS

*The Application of Hybrid Simulation Road Simulation in Automotive Durability Development*. International Forum on Reliability Session of SAE China. Shanghai, PRC. September 2019

*The Synthetic 3DOF Wheel Force for Passenger Vehicle Based on Predicted Frequency Response Function Model*. SAE World Congress Experience 2018. Detroit, MI. April 2018

### STUDENTS CO-ADVISED

### DOCTORAL RESEARCH COOPERATION PROJECTS

Hui Zhou, MPhil/PhD, *Studying the Effect of Vehicle Dynamic Parameters on Ride Comfort*, University of Southampton, 2015

Xiao Wang, PhD Candidate, *Structural and Control Strategy Optimization for Spindle-Coupled Road Simulation Test Stand*, Harbin Institute of Technology, 2018-2019

#### **MASTERS THESES**

Jinzheng Xu, *Modellprädiktive Regelung in der Automatisierungstechnik*, Technische Universität Berlin, 2020 (Internship Instructor)

Tengfei Huang, [\*Research on NVH Evaluation of Automobile Based on Four-poster Test Bench\*](#), Harbin Institute of Technology Weihai, 2018

Decheng Jin, [\*Proving Ground Correlation Based on The Theory of Road Load Data Acquisition\*](#), Hebei University of Engineering, 2015

Jiankun Sun, [\*Research of Automobile Proving Grounds Relevance Effects on Vehicle Reliability Tests\*](#), Hebei University of Engineering, 2013

Chao Lin, [\*Lightweight Design and Study of C2 Sedan Body in White\*](#), Hebei University of Engineering, 2013

#### **UNDERGRADUATE RESEARCH**

Huaiyu Ye, *RC Self-Driving Car's Signal Lights and Obstacle Recognition Based on Computer Vision*, Tianjin University of Technology and Education, 2018

#### **OTHER ACTIVITIES**

Society of Automotive Engineers, Voluntary Author and Review, 2014-PRESENT

Tianjin Library Media Lending Department Volunteer, PRC, 2011

Wikipedia Editor Volunteer, Contributed [\*nine items on "Did You Know" section\*](#), 2010-2011

World Economic Forum: Annual Meeting of the New Champions, Tianjin, PRC, Volunteer, 2010



# Verification Report

*of*

## China Higher Education Student's Academic Transcript

Name: Xu Chengjie  
 Sex: Male  
 ID No.: 120101198906273036  
 Institution: Hebei University of Technology  
 Level: Undergraduate  
 Major: Vehicle Engineering  
 GPA: 2.9

Report No.: **10456075**  
 Date of Report: Dec. 17, 2018  
 Page: 1 of 4

**The Academic Transcript listed below is considered authentic.**

SUBJECT	GRADES	CREDITS	SUBJECT	GRADES	CREDITS
<b>2007-2008 SEMESTER 1</b>					
Cultivation of Ethics and Fundamentals of Law	78	2.5	The Modern and Contemporary Chinese History For Practice Course	Excellent	0.5
Fundamentals of Computer Culture A	82	3	Business Oral English	85	2
Economic Laws(1)	77	2	Physical education(2)	96	1
English (level 1)	71	4	General Physics Experiments A	Good	1.5
Advanced Mathematics(A)	93	5.5	Modern Chinese History	73	1.5
Practice:Cultivation of Ethics and Fundamentals of Law	Good	0.5	English (level 2)	79	4
physical education(1)	96	1	Design of Fundamental Software Technology	Excellent	1.5
<b>2007-2008 SEMESTER 2</b>			Advanced Mathematics (1)B	61	5.5
Linear Algebra	81	2	<b>(Continued on next page)</b>		
Principles of Management	74	3			



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China Higher Education Student Information  
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China Higher Education Student's Academic Transcript

Report No.: 10456075

Date of Report: Dec. 17, 2018

Page: 2 of 4

SUBJECT	GRADES	CREDITS	SUBJECT	GRADES	CREDITS
Summer Social Survey(1)	Good	2	Design of Mechanical Principle Course	Good	1.5
Fundamentals of Computer Software Technology(VC)	74	3.5	Mechanical Principles	72	4.5
<b>2008-2009 SEMESTER 1</b>			English (level 4)	81	4
General physics (1) B	88	3.5	Engineering Graphics(1)B	77	4
Principles of Marxism Practice Course	98	0.5	physical education(4)	78	1
English (level 3)	77	4	Materials of Mechanical Engineering	76	2
General Physics Experiments B	Excellent	1.5	Electrical and Electronic Technology Experiments(1) A	93	0.5
Engineering Graphics(1)A	80	4	Basic Knowledge of Unigraphics NX	60	2
Bridge Foundation	Medium	2	Metal working Practice 2	95	1
Metal working practice 1	Good	4	Electrical and Electronic Technology(1)A	77	2.5
physical education (3)	89	1	<b>2009-2010 SEMESTER 1</b>		
Engineering Mechanics (1) A	74	4	Fundamentals of Interchangeability and Measurement	88	2
Technology of Metals (2)	79	2	Technology Fundamentals of Control Engineering	81	3
Principles of Marxism	80	2.5			
<b>2008-2009 SEMESTER 2</b>					
Engineering Mechanics (1) B	60	4			
Probability Theory and Mathematical Statistics	83	3			

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SUBJECT	GRADES	CREDITS	SUBJECT	GRADES	CREDITS
Design of Mechanical Design Course	Medium	3	Mao Zedong Thought and Socialism with Chinese Characteristics(2)	85	0.5
Mechanical Design	78	5	Production practice	Good	3
Mao Zedong Thought and Socialism with Chinese Characteristics(1)	62	2.5	Vehicle Manufacturing Technology	78	4
Mao Zedong Thought and Socialism with Chinese Characteristics(1)	88	0.5	Mao Zedong Thought and Chinese characteristic socialism system info introduction (2)	75	2.5
Electrical and Electronic Technology	89.6	0.5	<b>2011-2012 SEMESTER 1</b>		
Experiments(1)B			Course Design of Major Direction	Excellent	3
Electrical and Electronic Technology(1)B	82	2.5	Professional English Reading	84	2
<b>2009-2010 SEMESTER 2</b>			Vehicle Drive	Good	1
Modern Design Method	69	2	Vehicle Manufacturing Process Course Design	Medium	2
Hydraulic and Pneumatic	89	3	Vehicle CAE	95	2
General physics (1) A	60	3.5	Structure and Principle of Automotive Body	60	2.5
Application of Freescale Embedded MicroController	92	2	<b>(Continued on next page)</b>		
Vehicle Structure	82	6			
Principle of Engine(1)	82	2.5			
Vehicle Experiment of Instrumentation	74	3.5			

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**China Higher Education Student's Academic Transcript**

Report No.: **10456075**  
Date of Report: **Dec. 17, 2018**  
Page: **4 of 4**

<b>SUBJECT</b>	<b>GRADES CREDITS</b>	
Special Vehicle Structure and Design	78	2
Automotive Safety Technology	74	2
Vehicle Vibration and Noise Control	86	2
Automotive Electronics and Electrical Equipment	80	2
Automotive Electronics Control	84	2.5
Vehicle Design	70	3.5
Theory of Vehicle Dynamic	74	3.5
<b>2011-2012 SEMESTER 2</b>		
Innovative design	74	2
Graduation Design (Thesis )	91	14

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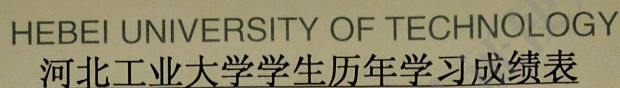


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China Higher Education Student Information  
and Career Center







毕业证书编号:

学位证书编号: 经济学

制表人：石亚茹

制表日期: 2011-06-21

第 1 页/共 1 页



## Seal of School of Mechanical Engineering of Hebei University of Technology

Graduation Certificate No.:  
Lister: Shi Yaru

Degree Certificate No.: Economics  
Generation Date: 2011-06-21

Page 1 of 1

I, Pan Zhanglin, staff of Hangzhou Qihang Translation Co., Ltd. confirm this is a true and accurate translation of the original document.

Translated by: Pan Zhangjin Contact Details: +86-0573-88599989

Qualification: TEM8 (Test for English Major - Band 8, Certificate No. E VIII 0810027416)

Organization: Hangzhou Qihang Translation Co., Ltd.

Organization Address: Room 503, Zheshang Venture Park, No.229, Xueyuan Street, Xiasha, Hangzhou

Signature: Panzhuang Date of Translation: 2018.11.13





## 《河北工业大学学籍管理规定（试行）》

2019-09-18 17:38:00 点击: 4944

### 第一章 总 则

第一条 为维护学校正常的教育教学秩序,促进学生德、智、体、美全面发展,根据教育部《普通高等学校学生管理规定》,结合我校实际情况,特制定本规定。

第二条 学生应遵守法律、法规,遵守《高等学校学生行为准则》和学校的各项规章制度。

第三条 本规定适用于我校接受普通高等学历教育的在校本科学子学籍管理。

### 第二章 学籍与学年年限

第四条 本校实行学年制。全日制普通本科基本学制为四年(建筑学、城乡规划专业为五年)。学生在校学习实行弹性学习年限,可提前或延迟完成学业。

学生在校学习最长年限(自入学学习起连续计算):可在基本学制基础上延长二年;可提前一年毕业。

### 第三章 入学与注册

第五条 按照国家和学校规定录取的新生,持录取通知书和学校规定的有关证件,按期办理入学手续。

(一)因故不能按期入学者,应当事先向学校请假并提交请假证明,逾期不报者,视为放弃入学资格。请假时间不得超过两周。未经请假或请假逾期者,除因不可抗力等正当事由外,视为放弃入学资格,由学院报教务处处理,取消其入学资格。

第七条 新生入学后二个月内,按照学校规定进行复查。复查工作由学院负责实施。复查合格予以注册,正式取得学籍。复查不合格者取消学籍手续。

(二)新生可以申请转入本校其他专业学习。申请转入本校其他专业学习的新生应当在报到时提交书面申请,家长签字,学院签署意见,教务处批准。两周内未办成转入手续者,视为放弃入学资格。

第八条 新生入学后,由学生所在学院根据录取专业组招生填写《入学学籍卡片》、《学生登记表》和《学生卡片》。《入学学籍卡片》送交教务处,《学生登记表》送交学工处,《学生卡片》由学生所在学院留存。

第九条 学生入学后,按照学校规定进行学籍注册。学籍注册合格予以注册,正式取得学籍。复查合格予以注册,正式取得学籍。复查不合格者取消学籍手续,将学籍档案予以处理,学籍取消入学资格。

第十条 新生在体检复查中发现患有疾病者,经学校指定的二级甲等以上医院(以上医院须经学校指定医院)诊断不宜在校学习的,且一年内治疗可达到健康标准的,可以保留入学资格一年。

(一)保留入学资格期间学校不予注册,学籍档案由学院保管。保留入学资格期间,学校不予注册,学籍档案由学院保管。

(二)保留入学资格期间,学校不予注册,学籍档案由学院保管。保留入学资格期间,学校不予注册,学籍档案由学院保管。

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